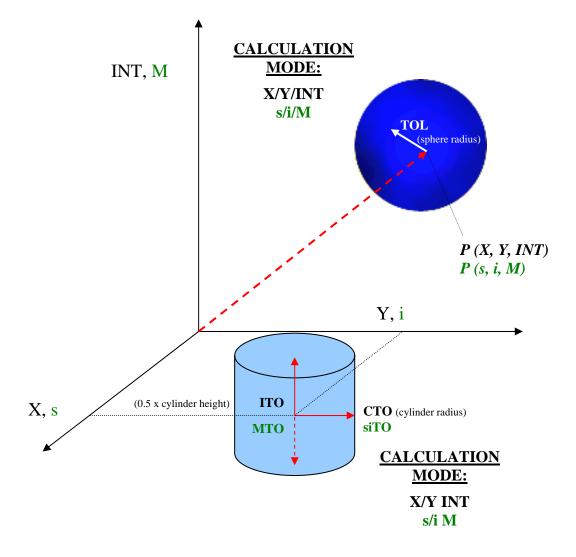
Short instructions for the operation of color sensors of the SPECTRO-3 series through software SPECTRO3-Scope V3.4

These instructions describe how to perform quick teaching of the color sensors of SPECTRO-3 series with the **SPECTRO3-Scope V3.4** software interface.

Basically there are 2 methods of teaching a color. These methods can be set with **CALCULATION MODE**.

The CALCULATION MODE X/Y/INT (or s/i/M) uses a color sphere in space with radius TOL. Contrary to this, the CALCULATION MODE X/Y INT (or s/i M) uses a color cylinder in space with radius CTO or siTO and with height ITO or M.

The teach process is the same for both methods. Color evaluation according to **s/i M** uses the Lab calculation method.



The text below describes a teach process with **EVALUATION MODE = BEST HIT** and **CALCULATION MODE = X/Y/INT**.

Step 1:

Prior to the use of the software aids (graphic display of sensor signals) the sensor must be manually adjusted to the respective target or background as accurately as possible. The reference distance of the sensor to the target is defined in the data sheet of the respective sensor.

Please make sure that the sensor is properly connected and supplied with power. Furthermore the sensor head must be directed onto the brightest surface (paper, leather, glass, etc.) of the color to be taught. This is absolutely necessary for being able to set a suitable **POWER** value for the sensor.

Step 2:

Start the SPECTRO3-Scope V3.4 software. Please check whether the status line at the right bottom displays the "SPECTRO3 V3.4 RT:KW*xx/xx* " message.

Info: Moving the mouse cursor to a control element and clicking with the right mouse button displays a short info on the respective individual control element.

SPECTRO3-SCOPE V3.4						
SPECTRO3-Scope V3.4						
CONNECT PARA1 PARA2 TEACH TABLE RECORDER CALIBRATE TABLE ATTRIBUTES POWER MODE STATIC Image: Constant of the state of the stat	SOURCE X 9 0 1 1 1 0 0 0 0 0	X/Y INT ▼ 10000- ● 9000- ● 8000- ● 7000- ● 6000- ● 5000- ● 4000- ● 3000- ● 2000- ● 0 2000 4000 0 2000 4000	TEMP 0			
RAM SEND GO EEPROM GET STOP		COMMUNICATION PORT 1 SPECTR03V3.4	RT:KW43/11			

🗮 THREE SIDE	S VIEW				
10000-		XX	4096-		RGB
8000-			3584-		
0000		- 18	3072-		
6000-			2560-		
4000-			2048-		
		- 18	1536-		
2000-		_	512-		
0-			0-		
0	5000	10000	0		100
10000-		X/INT	10000-		Y/INT
8000-		- 1	8000-		- 1
6000-		- 1	6000-		- 1
4000-		- 1	4000-		- 1
2000-		- 1	2000-		
0-, 0	5000	10000	0-, 0	5000	10000

Step 3:

Please make sure that for the time being **RAM** and not **EEPROM** is selected for the data exchange with the sensor (RAM is a volatile memory in the sensor, i.e. the data will be lost when power is turned off. EEPROM is a non-volatile memory in the sensor, i.e. the data will not be lost when power is turned off.)

All the other parameters should be set as shown in the picture below. Press the tab **PARA1** to show the parameters. (See the **FILE** function in the operating instructions for SPECTRO3-Scope.)

Now press the **GO** button. Data exchange between sensor and PC will then start. The contents for **RED**, **GREEN**, and **BLUE** that are diffusely reflected from the surface are represented as bars on the software interface. Set the POWER value in such a way that at least one of the three bars is in the upper third of its dynamic range, but none of them is in saturation. Ideally **POWER** and **GAIN** are set in such a way that **POWER** lies in the range of 200 to 800.

ATTENTION: The sensor must be informed when you have changed the **POWER** or **GAIN** value. Press the **SEND** button to send this information to the sensor. Check the bars by pressing **GO** again. Repeat this process until you have a suitable **POWER** value and **GAIN**.

Optimally the three bars should be at approximately the same level on white paper.

If the bars vary too much, you need to perform white light balancing.

(For white light balancing see the SPECTRO3-Scope operation instructions on the supplied CD.)

Tip! There is a trick for finding a suitable **POWER** value in no time at all. Set **POWER MODE = DYNAMIC**. The sensor then tries to find a suitable **POWER** value. Check this by pressing **GO**. Press **STOP** when the bars have "levelled out". Then press **GET**. The **POWER** value that was found now is shown in the **POWER** function field. Now set **POWER MODE = STATIC**, and press **SEND**.

** SPECTRO3-SCOPE V3.4						
SPECTRO3-Scope V3.4						
CONNECT PARA1 PARA2 TEACH TABLE RECORDER CALIBRATE TABLE ATTRIBUTES	SOURCE ×	X/Y/INT TEMP 18				
POWER MODE STATIC POWER (pm) 823 0 500 1000	942 Y 936	9000- 8000-				
Ó 500 1000 LED MODE AC ▼ DYNWIN HI 3300 GAIN AMP7 ▼ DYNWIN LO 3200	INT 1985	7000-				
AVERAGE 1	delta C	5000- 4000-				
MAXCOL-No. 10 OUTMODE BINARY 1	-1 C-No: 255					
EVALUATION MODE BEST HIT CALCULATION MODE X/Y/INT EXTEACH OFF TRIGGER CONT		1000- 				
RAM SEND GO EEPROM GET STOP		о 500 1000 1500 2000 2500 3000 3500 4096 СОММИЛІСАТІОЛ РОВТ 1 SPECTRO3 V3.4 ВТ:КW43/11				

Step 4: An X and a Y coordinate as well as an intensity INT are calculated from the red, green, and blue data. X = (R*4095) / (R+G+B)Y = (G*4095) / (R+G+B)INT = (R+G+B) / 3

Press the GO button once again to read out the current data.

Press **STOP** to stop the data exchange.

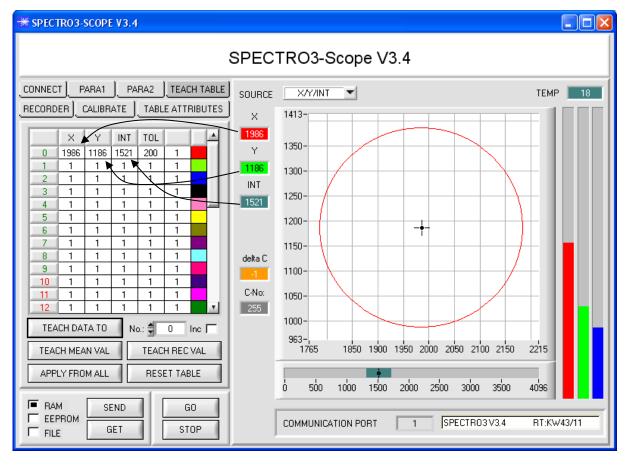
Now use the **TEACH TABLE** tab to switch to the **TEACH TABLE**.

Select a row under No.: to which the currently present color should be taught.

(ATTENTION: Only the rows marked with green numbers are evaluated by the sensor. If you want to teach more colors, use the MAXCOL-No. parameter to select how many colors you want to teach.)

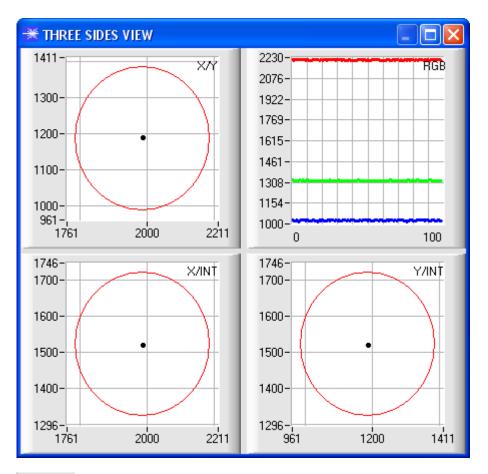
Now press the **TEACH DATA TO** button. The calculated values for **X**, **Y**, and **INT** are transferred to the **TEACH TABLE** in the row that was selected under **No.**:

The graphic display then shows a circle. This is the tolerance circle for the color. The radius of this circle can be set under **TOL** (tolerance). To change the **TOL** value please double-click on the corresponding cell in the **TEACH TABLE** with the left mouse button. In the small graph the current intensity **INT** with the tolerance window set under **No.:** is displayed in turquoise.



Now press the **SEND** button again to inform the sensor about the taught color. Then activate the **GO** mode again. When the sensor recognises a row vector (color), the corresponding row number is visualised on the software interface under **C-No:** A value of 255 means that none of the taught colors were recognised.

As you know the **X/Y/INT** mode uses a **color sphere** in space. To provide a better visual representation of this sphere, an additional panel is displayed here that shows the color sphere in a three-side view with the axes **X/Y**, **X/INT**, and **Y/INT** (see picture below).





A color is only recognised if its current coordinates lie in the tolerance circle.

Step 5:

For teaching additional colors please make sure that the sensor head is directed onto the respective color. Then repeat the procedure starting from step 4.

Step 6:

When you have taught all the channels, please select **EEPROM** and press **SEND** to save the data to the non-volatile memory of the sensor.